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Beyond Client-Server (part 2) Collective Communication

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Recall

- Last time: apps based on group vs. client-server interactions
 - Multicast as a communication primitive
 - Implemented in the network (L3) or as an overlay (L7)
 - Our context: the Internet at large
- Today: distributed training as our app
 - Also based on groups of hosts that communicate
 - But very different context: a single datacenter, different goals, *etc.*
 - Leading to new communication primitives: collectives

Outline

- Quick review: Overlays
- Context on distributed training: app and infrastructure
- Communication collectives: definitions and the function they provide
- How collectives are implemented
 - Focus on one collective: AllReduce
 - Implementation at overlay and underlay level



A virtual network (the "overlay") on top of an underlying physical network (the "underlay")



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Training: 10,000 ft. view (for CS168)



Distributed Training: 10,000 ft. view (for CS168)



Collective Communication

- A group of nodes that exchange data in a coordinated manner as part of a group computation
- Nature of this exchange depends on the details of the training and its parallelization
- Distilled into a foundational set of communication patterns referred to as "collectives"
- This lecture: **what** are these collectives and h**ow are they implemented** in the network
 - We won't get into **why** training/parallelization leads to these particular patterns

Distributed Training Infrastructure

- Nodes are specialized Graphics Processing Units (GPUs) or Tensor Processing Units (TPUs)
 - Typical scale: few 100s up to tens of 1000s
- Typically interconnected by a **dedicated datacenter-like** network
 - Dedicated \rightarrow not shared with other jobs/apps
 - Datacenter-like \rightarrow
 - Physically close
 - Regular topology (Clos, Torus)
 - Homogeneous
 - High bandwidth

Distributed Training Infrastructure



Source: Nvidia

Distributed Training Infrastructure: GPUs



Distributed Training Infrastructure: TPUs





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Collective Communication

- Coordinated exchange of data between a group of nodes (as part of a group computation)
- Originally designed for supercomputers running high-performance computing (HPC) apps
- Now widely used for AI workloads
 - Nvidia Collectives Communication Library (NCCL)
 - MS Azure MSCCL
 - TCCL, TE-CCL, ...

A quick example for intuition

(Will return for a deeper look shortly)



Collectives: common characteristics

• Synchronized: nodes (GPUs/TPUs) invoke and execute the collective operation in parallel

Machine 1Machine 2comm = communicator.create()comm = communicator.create()a = [1, 2, 3]a = [1, 0, 1]b = comm.allreduce(a, op=sum)b = comm.allreduce(a, op=sum)assert b == [2, 2, 4]assert b == [2, 2, 4]

Collectives: common characteristics

- Synchronized: nodes (GPUs/TPUs) invoke and execute the collective operation in parallel
- Orchestrated: centralized job scheduler distributes membership info, member IDs, roles, *etc.*
- Homogeneous: all nodes have same resources (compute, BW) and running same code
- **Blocking** (implicit or explicit): collective must complete at all nodes before proceeding
- Data may be **transformed** at intermediate hops in the communication path

Collectives: taxonomy and key operations

- Data redistribution (about moving data)
 - Broadcast
 - Scatter
 - Gather
 - AllGather
- Data consolidation (about moving and aggregating or "reducing" the data)*
 - Reduce
 - Reduce-Scatter
 - AllReduce

*We'll assume that aggregation = sum

Notation

- Number of nodes: *p* (=4 in most of our examples)
- Vector of data being exchanged: *x*
- For some operations, *x* is subdivided into subvectors x_i, i=0, 1, ... *p*-1
- Superscript denotes a vector that must be summed with vectors from other nodes:

 $\sum_{j} x_{i}^{(j)}$ indicates the sum of the subvector x_{i} from all nodes j

Let's now look at our set of collectives ...

Broadcast (p=4)

| Operation | Before | After | | | |
|-----------|------------------------------|--|--|--|--|
| Broadcast | Node 0Node 1Node 2Node 3 x | Node 0Node 1Node 2Node 3 x x x x | | | |



Scatter (p=4)

| Operation | Before | | | | After | | | |
|-----------|--|--------|--------|--------|-----------------------------|--------------|--------------------------|--------------------------|
| Scatter | Node 0 x_0 x_1 x_2 x_3 | Node 1 | Node 2 | Node 3 | $\frac{\text{Node 0}}{x_0}$ | Node 1 x_1 | Node 2 x ₂ | Node 3 x ₃ |



ref: Chan et al. Concurrency and Practice, 2007

Gather (p=4)

| Operation | | Be | fore | | After | | | |
|-----------|--------------|--------------|--------------|--------------------------|--|--------|--------|--------|
| Gather | Node 0 x_0 | Node 1 x_1 | Node 2 x_2 | Node 3 x ₃ | $ Node 0 x_0 x_1 x_2 x_3 $ | Node 1 | Node 2 | Node 3 |



node i sends its ith subvector to a target node

ref: Chan et al. Concurrency and Practice, 2007

AllGather (p=4)

| Operation | | | After | | | | | |
|-----------|--------------|--------------|-----------------|--------------------------|--|--|--|--|
| Allgather | Node 0 x_0 | Node 1 x_1 | Node 2 x_2 | Node 3 x ₃ | $ \begin{array}{c} \text{Node 0} \\ \hline x_0 \\ x_1 \\ x_2 \\ x_3 \\ \end{array} $ | Node 1 x_0 x_1 x_2 x_3 | Node 2 x_0 x_1 x_2 x_3 | Node 3 $\begin{array}{c} x_0 \\ x_1 \\ x_2 \\ x_3 \end{array}$ |



Node i sends its ith subvector to all

ref: Chan et al. Concurrency and Practice, 2007

Collectives: taxonomy and key operations

- **Data redistribution** (about moving data)
 - Broadcast
 - Scatter
 - Gather
 - AllGather
- Data consolidation (about moving *and* aggregating the data)*
 - Reduce
 - Reduce-Scatter
 - AllReduce

Reduce (p=4)

| Operation | Before | After | | | |
|---------------------|--|--|--|--|--|
| Reduce(- to-one) | $\begin{array}{c c c c c c c c c c c c c c c c c c c $ | Node 0 Node 1 Node 2 Node 3 $\Sigma_j x^{(j)}$ | | | |



All nodes' vectors are summed at a target node

ReduceScatter (p=4)

| Operation | Before | After |
|--------------------|--|---|
| Reduce- scatter | $\begin{array}{c c c c c c c c c c c c c c c c c c c $ | Node 0Node 1Node 2Node 3 $\Sigma_j x_0^{(j)}$ $\Sigma_j x_1^{(j)}$ $\Sigma_j x_2^{(j)}$ $\Sigma_j x_2^{(j)}$ $\Sigma_j x_0^{(j)}$ $\Sigma_j x_1^{(j)}$ $\Sigma_j x_2^{(j)}$ |



The i^th subvector from all nodes is summed at node i

AllReduce (p=4)

| Operation | Before | After | | | |
|-----------|--|--|--|--|--|
| Allreduce | Node 0Node 1Node 2Node 3 $x^{(0)}$ $x^{(1)}$ $x^{(2)}$ $x^{(3)}$ | Node 0Node 1Node 2Node 3 $\Sigma_j x^{(j)}$ $\Sigma_j x^{(j)}$ $\Sigma_j x^{(j)}$ $\Sigma_j x^{(j)}$ | | | |



All nodes have the sum of all nodes' vectors



Some collectives are <u>duals</u> of each other

- Collectives C1 and C2 are duals if *reversing* the communication in C1 yields C2
 - Reversing means $A \rightarrow B$ becomes $B \rightarrow A$
 - We ignore any computation when determining duality

• For a given topology/routing scheme, a collective and its dual see equivalent performance

Broadcast and Reduce are duals

| Operation | Before | After | | | |
|---------------------|--|--|--|--|--|
| Broadcast | Node 0Node 1Node 2Node 3 x | Node 0Node 1Node 2Node 3 x x x x x | | | |
| Reduce(- to-one) | Node 0Node 1Node 2Node 3 $x^{(0)}$ $x^{(1)}$ $x^{(2)}$ $x^{(3)}$ | Node 0 Node 1 Node 2 Node 3 $\Sigma_j x^{(j)}$ $ $ $ $ | | | |

Scatter and Gather are duals

| Operation | Before | | | | After | | | |
|-----------|--|-----------------|--------------|--------------------------|--|--------------|--------------------------|--------------------------|
| Scatter | Node 0 x_0 x_1 x_2 x_3 | Node 1 | Node 2 | Node 3 | Node 0 x_0 | Node 1 x_1 | Node 2 x ₂ | Node 3 x ₃ |
| Gather | Node 0 x_0 | Node 1 x_1 | Node 2 x_2 | Node 3 x ₃ | $ Node 0 x_0 x_1 x_2 x_3 $ | Node 1 | Node 2 | Node 3 |

AllGather and ReduceScatter are duals

| Operation | Before | | | | After | | | |
|--------------------|--|--|--|--|--|--|--|--|
| Allgather | Node 0 x_0 | Node 1 x_1 | Node 2 x ₂ | Node 3 x ₃ | $ Node 0 x_0 x_1 x_2 x_3 $ | Node 1 x_0 x_1 x_2 x_3 | Node 2 x_0 x_1 x_2 x_3 | Node 3 x_0 x_1 x_2 x_3 |
| Reduce- scatter | Node 0 $x_0^{(0)}$ $x_1^{(0)}$ $x_2^{(0)}$ $x_3^{(0)}$ | Node 1 $x_0^{(1)}$ $x_1^{(1)}$ $x_2^{(1)}$ $x_3^{(1)}$ | Node 2 $x_0^{(2)}$ $x_1^{(2)}$ $x_2^{(2)}$ $x_3^{(2)}$ | Node 3 $x_0^{(3)}$ $x_1^{(3)}$ $x_2^{(3)}$ $x_3^{(3)}$ | $\frac{\text{Node 0}}{\sum_j x_0^{(j)}}$ | Node 1 $\Sigma_j x_1^{(j)}$ | Node 2 $\Sigma_j x_2^{(j)}$ | Node 3 $\Sigma_j x_3^{(j)}$ |

AllReduce does not have a dual

Note: AllReduce = ReduceScatter + AllGather (Convince yourself of this later!)

Outline

• Context on distributed training: app and infrastructure

• Communication collectives: definitions and the function they provide

• How collectives are implemented

• We'll focus on one collective: AllReduce

Implementing AllReduce

- Let's consider the simplest implementation: a full mesh of node-to-node exchanges
 - Every node sends its vector **x** directly to every other node
 - Each node sums all the vectors it receives
- Assuming *p* nodes and that vector *x* is of size **D** bytes:
 - Each node implements *p-1* transmit, receive, and summation operations
 - Each on a vector of size D bytes
 - Total traffic in the network: **O(p² x D)**
 - Consider D ~100s of GB and p ~ 1000s of nodes
- Need a more scalable solution!

Implementing AllReduce ... using overlays

- Idea: construct a virtual topology between the *p* nodes; "reduce" (sum) data as it traverses the overlay
- Details vary depending on the virtual topology selected
- Two typical choices: tree or ring







- Nodes form a logical tree; aggregate to the root and then broadcast
 - Leaf node: transmits vector to its parent
 - Every intermediate node
 - aggregates (sums) its own vector with that from each child node
 - send the resulting (aggregated) vector to its parent
 - Root broadcasts the final aggregated vector down the tree
- Assuming a binary tree with *p* nodes and vector of **D** bytes:
 - AllReduce involves O(log P) steps *to travel up and down the tree*
 - Each node implements **3** transmit, receive, and summation operations , each on a vector of size D bytes
 - Total traffic in the network: **O(p x D) across all steps** *much better than with the mesh!*



• Initial step: node i sends i^th subvector to its predecessor on the ring



- Initial step: node i sends i^th subvector to its predecessor on the ring
- When a node receives the kth subvector from its successor, it adds this to its own kth subvector and in the next step, sends this (aggregated) kth subvector to its predecessor

In reality: we sent a single subvector equal to the sum of these subvectors (not showing the aggregated subvector for illustration purposes only)



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- After p-1 steps, the successor of node i will have the fully aggregated i^th subvector



- Initial step: node i sends i^th subvector to its predecessor on the ring
- When a node receives the kth subvector from its successor, it adds this to its own kth subvector and in the next step, sends this (aggregated) kth subvector to its predecessor
- After p-1 steps, the successor of node i will have the fully aggregated i^th subvector
- Repeat (without aggregation); after p-1 steps all nodes have the entire reduced vector!

- Process
 - Initial step: node i sends i^th chunk to its predecessor on the logical ring
 - When a node receives the kth chunk from its successor, it adds this to its own kth chunk and in the next step, sends this (aggregated) kth chunk to its predecessor
 - After p-1 steps, the successor of node i will have the fully aggregated i^th chunk
 - Repeat but now without aggregation; after p-1 steps all nodes have the entire reduced vector!
- Assuming a ring with *p* nodes and vector of **D** bytes:
 - Takes ~2*p* steps
 - In each step, a node transmits/receives/sums a subvector of size D/p bytes
 - Total traffic in the network across all steps: **O**(*p* **x D**)

Taking Stock

Three levels at which we can view communication collectives:

• Definition or "service model"

• Overlay viewpoint

• Underlay (physical network) viewpoint



Closing point:



How do we assign overlay nodes to physical GPUs so as to achieve low "stretch" (last lecture)?

Questions?